

Graphical Modeling of High-Throughput Metabolomics Data

Differential Networks pertaining to Alzheimer's Disease

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Outline



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Omics and omics data

-ome

A totality of some (molecular biological) sort

-omics

Collective quantification of some pool of molecular molecules

Metabolomics

The omics of small-molecule metabolites (of some organism)

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Metabolite quantification



Illustration adapted from: http://planetorbitrap.com/untargeted-metabolomics#.Vzw6yfmLRaQ &

http://metabolomicsplatform.com/metabolomics-overview/

CFWP

Graphical Modeling Metabolomics

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Challenge: Dimensionality metabolomic data

	Variables		Variables (features)
	1 2 3 ····· <i>p</i>	1 2 3	4 5 · · · · · · p
1	$y_{11} \ y_{12} \ y_{13} \cdots y_{1p}$	1 y ₁₁ y ₁₂ y ₁	₃ y ₁₄ y ₁₅ y _{1p}
tions 5	$y_{21} \ y_{22} \ y_{23} \cdots y_{2p}$		³ y ₂₄ y ₂₅ y _{2p}
serva 3	$y_{31} \ y_{32} \ y_{33} \cdots \cdots y_{3p}$	X 3 Y ₃₁ Y ₃₂ Y ₃₁	³ Y ₃₄ Y ₃₅ Y _{3p}
ê 4	$y_{41} \ y_{42} \ y_{43} \cdots y_{4p}$	ð :	
5 	Y51 Y52 Y53 Y5p		

Regular data: n > p

Metabolomic data: p > n or p >> n

Unit of analysis



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Motivation

Desire

- Consider data from multiple metabolomic platforms simultaneously
- Exploratively infer graph (reconstruct metabolic topology)
- Cope with high-dimensional situation
- Take juxtaposition AD vs. SC formally into account

Graphs

Representation

Pathways are represented by a graph (or network)

Vertices

○ Node or vertex represents molecular feature

Edges

Edge or arrow represents some functional relation



Example

Three variables: Y_1, Y_2 , and Y_3





Marginal dependence

Undirected edge represents marginal dependence

Interpretational danger









True mechanism

Not observing Y_1 : Spurious association Observing Y₁: Saturated graph

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Solution: Conditioning



Solution: Conditioning





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Conditional dependence

Partial correlation

Measures degree of association between two random variables when controlling for third variables

Conditioned correlation

 $cor(Y_1, Y_2|Y_3)$ $cor(Y_1, Y_3 | Y_2)$ $cor(Y_2, Y_3 | Y_1)$

If, e.g., $cor(Y_2, Y_3|Y_1) = 0$, we say Y_2 and Y_3 are independent given Y_1





Gaussian graphical modeling

Graphical modeling

Class of models using graphs to express conditional (in)dependence relations between random variables

Gaussian setting

- Vertices: Correspond to random variables with normal distribution
- Edges: Correspond to the dependence structure
- Say $\mathbf{y} \sim \mathcal{N}_p(\mathbf{0}, \mathbf{\Sigma})$, and define $\mathbf{\Sigma}^{-1} \equiv \mathbf{\Omega}$. Then, for $a, b \in$ vertex set V, $a \neq b$



Gaussian graphical modeling

$$oldsymbol{\Omega} = \left[egin{array}{ccc} \omega_{11} & \omega_{12} & \omega_{13} \ \omega_{21} & \omega_{22} & 0 \ \omega_{31} & 0 & \omega_{33} \end{array}
ight]$$



Conditional independence graph

$$\mathbf{\Sigma} = \mathbf{\Omega}^{-1} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$



Correlation graph

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Full-Swing back to Challenge: High-dimensional data



Problem

- Let $\boldsymbol{S}\equiv\hat{\boldsymbol{\Sigma}}$ denote the sample covariance matrix on \mathbf{y}_{i}
- When $p \approx n$ or p > n, **S** is ill-behaved or singular
- $\bullet\,$ The precision ${\bm S}^{-1}\equiv \hat{\bm \Omega}$ is then undefined

A (1) > A (2) > A

Solution: ℓ_2 -Penalization

Maximize

$$\underbrace{ \mathsf{ln} \, |\boldsymbol{\Omega}| - \mathsf{tr}(\boldsymbol{S}\boldsymbol{\Omega})}_{\mathrm{log-likelihood}} - \underbrace{\frac{\lambda}{2} \|\boldsymbol{\Omega} - \boldsymbol{\mathsf{T}}\|_2^2}_{\ell_2 - \mathrm{penalty}}$$

- T denotes a p.d. symmetric target matrix
- $\lambda \in (0,\infty)$ denotes a penalty parameter

Analytic penalized ML estimator

$$\hat{\mathbf{\Omega}}(\lambda) = \left\{ \left[\lambda \mathbf{I}_{
ho} + rac{1}{4} (\mathbf{S} - \lambda \mathbf{T})^2
ight]^{1/2} + rac{1}{2} (\mathbf{S} - \lambda \mathbf{T})
ight\}^{-1}$$

Multiple data classes



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Targeted fused ridge estimation

Maximize

$$\mathcal{L}\left(\{\boldsymbol{\Omega}_{g}\};\{\boldsymbol{\mathsf{S}}_{g}\}\right) - \frac{\lambda}{2} \sum_{g} \left\|\boldsymbol{\Omega}_{g} - \boldsymbol{\mathsf{T}}_{g}\right\|_{F}^{2} - \frac{\lambda_{f}}{4} \sum_{g_{1},g_{2}} \left\|\left(\boldsymbol{\Omega}_{g_{1}} - \boldsymbol{\mathsf{T}}_{g_{1}}\right) - \left(\boldsymbol{\Omega}_{g_{2}} - \boldsymbol{\mathsf{T}}_{g_{2}}\right)\right\|_{F}^{2}$$

- T_g indicate class-specific target matrices
- $\lambda \in (0,\infty)$ denotes the ridge penalty parameter
- $\lambda_f \in [0,\infty)$ denotes the fusion penalty parameter

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Approach

Steps

- Class precision matrices were estimated by ridge fusion
- Optimal penalty parameters were determined by cross-validation
- Class-specific target matrices expressed little prior information
- Support determination on the basis of thresholding
 - retain strongest edges: corresponds to posterior probability thresholding
- Subsequent focus on differential network visualization and analysis

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SC Connections



AD Connections



Shared Connections



Differential Connections



Differential Connections



Differential Connections





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Explaining the inverse

The scalar inverse

- Let a denote a number (excluding 0)
- The inverse is then the number *b* such that $a \times b = 1$
- Clearly, $b = \frac{1}{a}$

Matrix

A matrix is a generalization of a number, an array of numbers

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1p} \\ a_{21} & a_{22} & \cdots & a_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ a_{p1} & a_{p2} & \cdots & a_{pp} \end{bmatrix}$$

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Explaining the inverse

The Matrix Inverse

Consider the matrix **A**. Its inverse $\mathbf{B} = \mathbf{A}^{-1}$ is defined such that

AB = I,

where

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

Solution

$$\mathbf{A}^{-1} = \left[\begin{array}{cc} \mathbf{A}_{11}^{-1} + \mathbf{A}_{11}^{-1} \mathbf{A}_{12} \mathbf{Q}^{-1} \mathbf{A}_{21} \mathbf{A}_{11}^{-1} & -\mathbf{A}_{11}^{-1} \mathbf{A}_{12} \mathbf{Q}^{-1} \\ -\mathbf{Q}^{-1} \mathbf{A}_{21} \mathbf{A}_{11}^{-1} & \mathbf{Q}^{-1} \end{array} \right]$$

with $\bm{Q}=\bm{A}_{22}-\bm{A}_{21}\bm{A}_{11}^{-1}\bm{A}_{12}$ denoting the Schur complement.

Appendix

Matrix Inverse

Singularity



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Recall: ridge estimation

Analytic maximizing argument

$$\hat{\mathbf{\Omega}}(\lambda) = \left\{ \left[\lambda \mathbf{I}_p + rac{1}{4} (\mathbf{S} - \lambda \mathbf{T})^2
ight]^{1/2} + rac{1}{2} (\mathbf{S} - \lambda \mathbf{T})
ight\}^{-1}$$

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Properties

Behavior

i. $\hat{\Omega}(\lambda) \succ 0$, for all $\lambda \in (0, \infty)$; ii. $\lim_{\lambda \to 0^+} \hat{\Omega}(\lambda) = \mathbf{S}^{-1}$ if p < n; iii. $\lim_{\lambda \to \infty} \hat{\Omega}(\lambda) = \mathbf{T}$.

Consistency

i.
$$\lim_{n\to\infty} \mathbb{E}\left[\hat{\Omega}_n(\lambda_n)\right] \longrightarrow \lim_{n\to\infty} \mathbb{E}\left(\mathbf{S}_n^{-1}\right) = \mathbf{\Omega};$$

ii. $\lim_{n\to\infty} \mathbb{E}\left(\|\hat{\Omega}_n(\lambda_n) - \mathbf{\Omega}\|_F^2\right) = 0.$

Visual explanation



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Choosing the penalty value

K-fold cross-validation (CV)

Single iteration of *K*-fold CV



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Choosing the penalty value

K-fold CV score

$$\varphi^{\kappa}(\lambda) = \sum_{k=1}^{\kappa} n_k \left\{ -\ln |\hat{\boldsymbol{\Omega}}(\lambda)_{-k}| + \operatorname{tr}[\hat{\boldsymbol{\Omega}}(\lambda)_{-k} \mathbf{S}_k] \right\},\,$$

 n_k is the size of subset k, for $k = 1, \ldots, K$ disjoint subsets; \mathbf{S}_k denotes the sample covariance matrix on *kth* test set; $\hat{\mathbf{\Omega}}(\lambda)_{-k}$ denotes the estimated regularized precision matrix on *kth* training set

Highest predictive accuracy

Choose $n_k = 1$, such that K = n (known as leave-one-out CV - LOOCV)

Problem

K-fold CV is computationally demanding for large p and/or large K

Solution

Computationally efficient approximate LOOCV score

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Support determination

Scaling

 $\hat{\mathbf{P}}(\lambda)$: Regularized precision estimate scaled to partial correlation form

Assume

Nonredundant off-diagonal partial correlation coefficients (indexed by j < j') follow a mixture distribution:

$$f\left\{\left[\hat{\mathbf{P}}(\lambda^{*})\right]_{jj'}\right\} = \eta_{0}f_{0}\left\{\left[\hat{\mathbf{P}}(\lambda^{*})\right]_{jj'};\kappa\right\} + (1-\eta_{0})f_{\mathcal{E}}\left\{\left[\hat{\mathbf{P}}(\lambda^{*})\right]_{jj'}\right\}$$

- $\eta_0 \in [0,1]$ is the mixture weight
- $f_0\{\cdot\}$ denotes the distribution of a null-edge
- $f_{\mathcal{E}}\{\cdot\}$ denotes the distribution of a present edge

Determine

$$P\left(Y_{j} \neq Y_{j'} | [\hat{\mathbf{P}}(\lambda^{*})]_{jj'}
ight)$$

Situation

Data

- G classes of $(n_g \times p)$ -dimensional data
- Classes defined by data sets and/or (subtypes of) diseases

Assumption

Precision matrices of constituent classes chiefly share the same structure but potentially differ in a number of locations of interest

Desire

Integrative or meta-analytic Gaussian graphical modeling

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Targeted fused ridge estimation: General Formulation

Maximize

$$\underbrace{\mathcal{L}\left(\{\boldsymbol{\Omega}_{g}\};\{\boldsymbol{\mathsf{S}}_{g}\}\right)}_{\text{log-likelihood}} - \sum_{g} \underbrace{\frac{\lambda_{gg}}{2} \left\|\boldsymbol{\Omega}_{g} - \boldsymbol{\mathsf{T}}_{g}\right\|_{F}^{2}}_{\text{ridge-penalty}} - \sum_{g_{1},g_{2}} \underbrace{\frac{\lambda_{g_{1}g_{2}}}{4} \left\|\left(\boldsymbol{\Omega}_{g_{1}} - \boldsymbol{\mathsf{T}}_{g_{1}}\right) - \left(\boldsymbol{\Omega}_{g_{2}} - \boldsymbol{\mathsf{T}}_{g_{2}}\right)\right\|_{F}^{2}}_{\text{fusion-penalty}}$$

- T_g indicate class-specific target matrices
- $\lambda_{gg} \in (0,\infty)$ denote class-specific ridge penalty parameters
- $\lambda_{g_1g_2} \in [0,\infty)$ denote pair-specific fusion penalty parameters, $\lambda_{g_1g_2} = \lambda_{g_2g_1}$

Penalty matrix

All penalties can be collected into a non-negative symmetric matrix $\mathbf{\Lambda} = [\lambda_{g_1g_2}]$

Targeted fused ridge estimation

Maximizing argument for class g_0

$$\hat{\boldsymbol{\Omega}}_{g_0} \left(\boldsymbol{\Lambda}, \{ \boldsymbol{\Omega}_g \}_{g \neq g_0} \right) = \left\{ \left[\bar{\lambda}_{g_0} \boldsymbol{\mathsf{I}}_{\rho} + \frac{1}{4} \left(\bar{\boldsymbol{\mathsf{S}}}_{g_0} - \bar{\lambda}_{g_0} \boldsymbol{\mathsf{T}}_{g_0} \right)^2 \right]^{1/2} + \frac{1}{2} \left(\bar{\boldsymbol{\mathsf{S}}}_{g_0} - \bar{\lambda}_{g_0} \boldsymbol{\mathsf{T}}_{g_0} \right) \right\}^{-1},$$

where

$$\bar{\mathbf{S}}_{g_0} = \mathbf{S}_{g_0} - \sum_{g \neq g_0} \frac{\lambda_{gg_0}}{n_{g_0}} (\mathbf{\Omega}_g - \mathbf{T}_g), \quad \text{and} \quad \bar{\lambda}_{g_0} = \frac{\sum_g \lambda_{gg_0}}{n_{g_0}}$$

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Properties

Behavior

i.
$$\hat{\Omega}_g \succ \mathbf{0}$$
 for all $\lambda_{gg} \in (0, \infty)$;
ii. $\lim_{\lambda_{gg} \to 0^+} \hat{\Omega}_g = \mathbf{S}_g^{-1}$ if $\sum_{g' \neq g} \lambda_{gg'} = 0$ and $p \leq n_g$;
iii. $\lim_{\lambda_{gg} \to \infty} \hat{\Omega}_g = \mathbf{T}_g$ if $\lambda_{gg'} < \infty$ for all $g' \neq g$;
iv. $\lim_{\lambda_{g_1g_2} \to \infty} (\hat{\Omega}_{g_1} - \mathbf{T}_{g_1}) = \lim_{\lambda_{g_1g_2} \to \infty} (\hat{\Omega}_{g_2} - \mathbf{T}_{g_2})$ if $\lambda_{g'_1g'_2} < \infty$ for all $\{g'_1, g'_2\} \neq \{g_1, g_2\}$.

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Block coordinate ascent

1: Input: 2: Sufficient data: $(S_1, n_1), ..., (S_G, n_G)$ 3: Penalty matrix: ∧ 4: Convergence criterion: $\varepsilon > 0$ 5: Output: 6: Estimates: $\hat{\Omega}_1, \ldots, \hat{\Omega}_G$ 7: procedure RIDGEP.FUSED($S_1, \ldots, S_G, n_1, \ldots, n_G, \Lambda, \varepsilon$) Initialize: $\hat{\Omega}_{\sigma}^{(0)}$ for all g. 8. for $c = 1, 2, 3, \dots$ do 9: for g = 1, 2, ..., G do 10. Update $\hat{\Omega}_{\sigma}^{(c)} := \hat{\Omega}_{\sigma}(\boldsymbol{\Lambda}, \hat{\Omega}_{1}^{(c)}, \dots, \hat{\Omega}_{\sigma-1}^{(c)}, \hat{\Omega}_{\sigma-1}^{(c-1)}, \dots, \hat{\Omega}_{\sigma-1}^{(c-1)})$ 11: end for 12. if $\max_{g} \left\{ \frac{\|\hat{\Omega}_{g}^{(c)} - \hat{\Omega}_{g}^{(c-1)}\|_{F}^{2}}{\|\hat{\Omega}_{x}^{(c)}\|_{F}^{2}} \right\} < \varepsilon$ then 13: return $(\hat{\Omega}_1^{(c)}, \dots, \hat{\Omega}_c^{(c)})$ 14: end if 15 end for 16: 17: end procedure

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